



Integration of mobile automated monitoring systems with decision support tools for smart HAB management

VITO
Jaap van Nes
Göteborg, May 2015

INDEX



1. Background VITO Belgium
2. HAB monitoring methods
3. Sensor platforms and developed sensor software
4. Mobile sensor platform
5. Service steps
6. Questions?

INTRODUCTION

- *Activities of VITO's land & water team:* study spatial environmental aspects in soil, groundwater and surface water by monitoring, modelling and risk assessment.
- *HAB:* cyano monitoring in surface water, data management, visualization and interpretation through sensor techniques on km scale for water boards, recreational lakes and drinking water companies.



1. VITO: A RESEARCH & TECHNOLOGY ORGANIZATION

- ❑ Foster innovation:
 - To improve quality of life
 - To build economic competitiveness.
- ❑ Bring together key players across the whole innovation chain.



1. VITO: NUMBERS



- 750 researchers
- 26 nationalities



- » More than 400 patents worldwide



- » Headquarters in Belgium (5 Locations)
- » Subsidiary in China



- » 200 scientific articles (2014)



- » 1000 research projects



- » € 140 M turnover in 2014

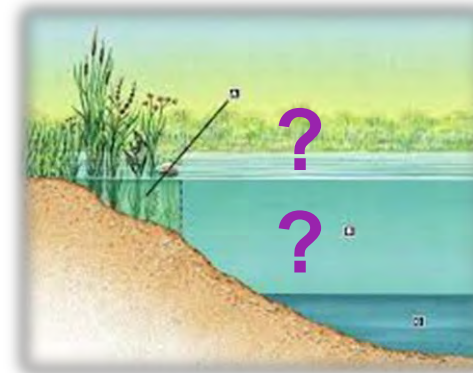


- » More than 500 research partners

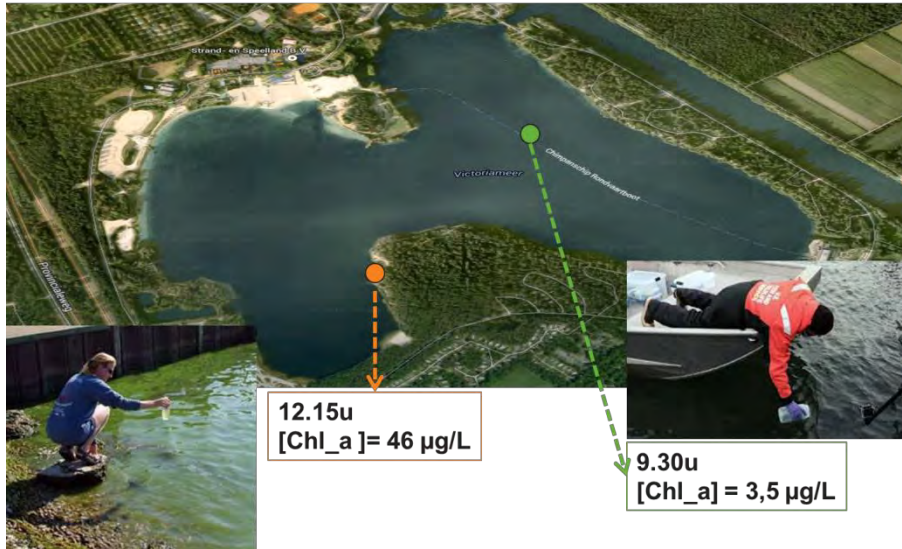
2. HAB MONITORING: WHERE AND WHEN?

Many variables to consider:

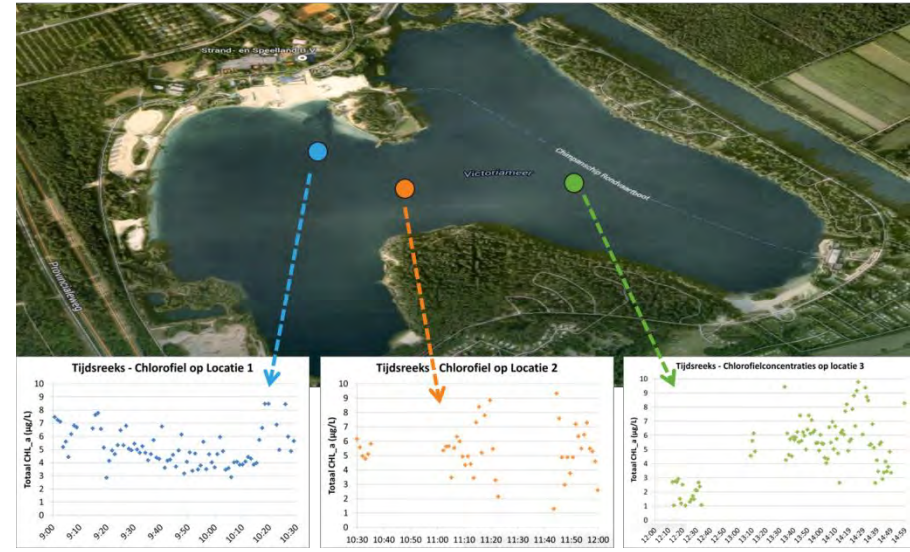
- Sun, shadow, precipitation?
- Open water, close to shores?
- Wind direction and velocity?
- Spatial variation, patterns?
- Temporal variation trends?
- Distance to emission sources?
- Water and sediment depth?
- Insight and system knowledge
- Available budget
- Targeted management.



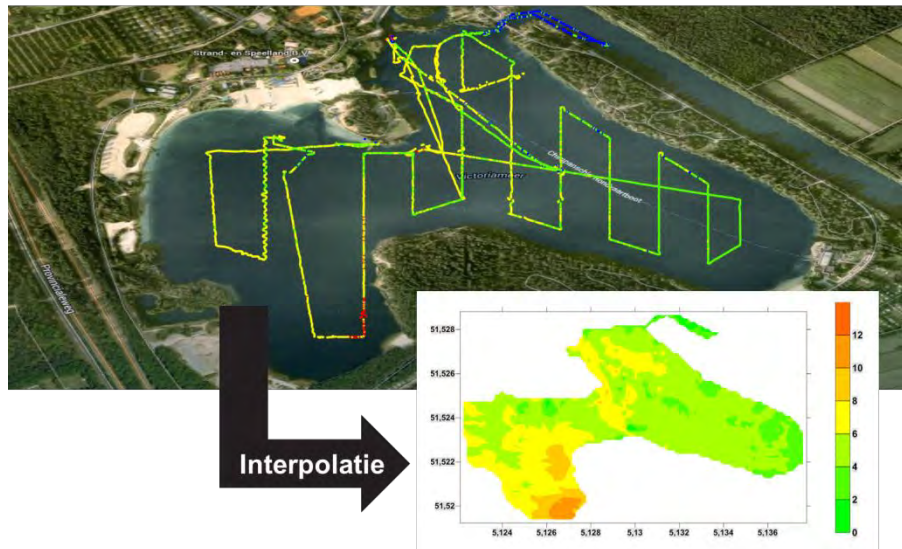
A) Spot sampling



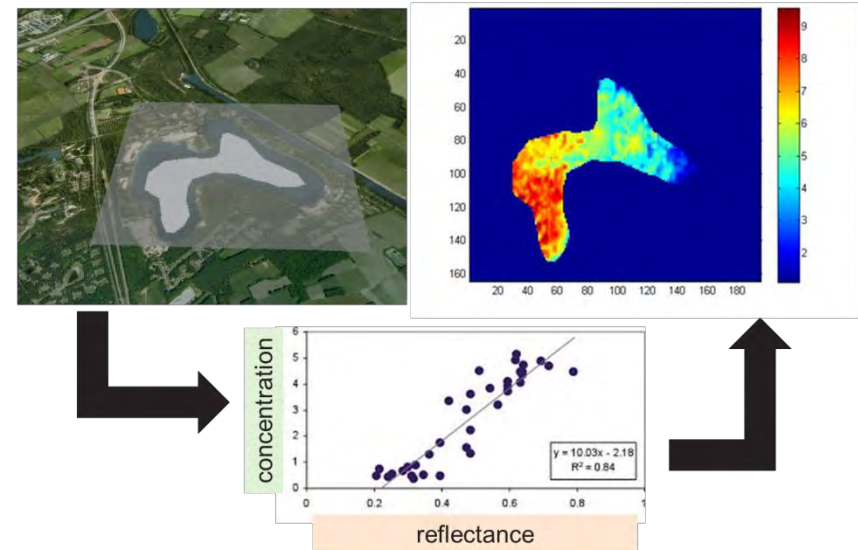
B) Fixed sensors



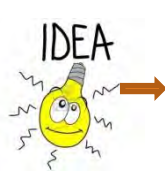
C) Mobile sensor platform



D) Earth observation



3. DEVELOPMENT PROCESS OF SENSOR SOFTWARE *SENSORVIEW*



2008



2009



2010



2011



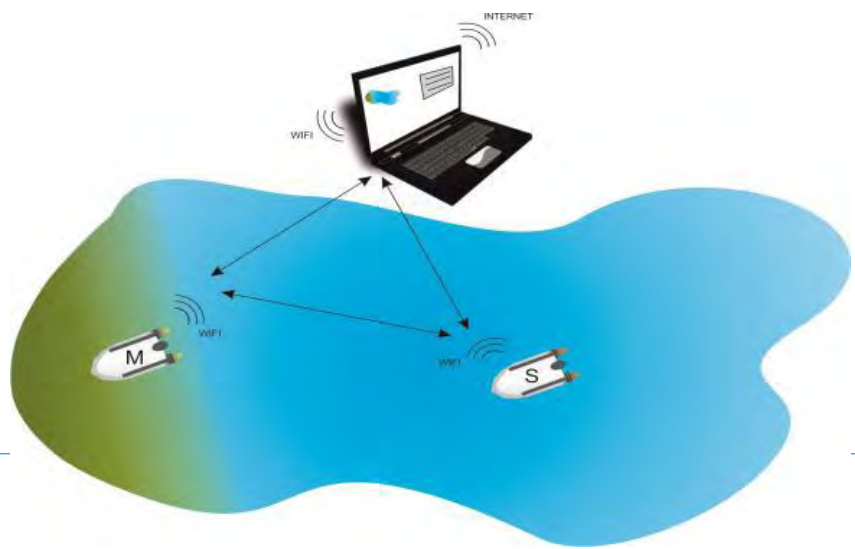
2012



2013

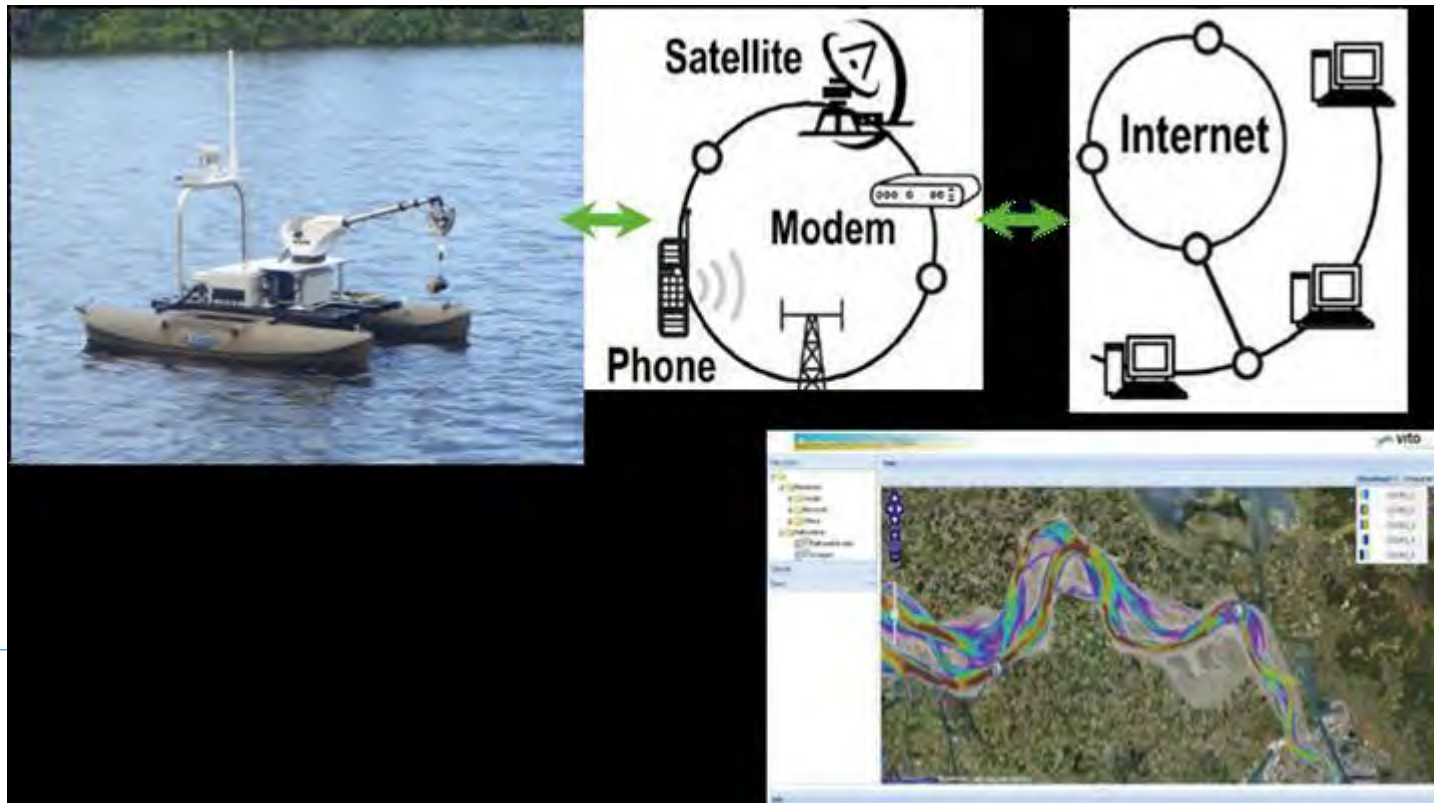


2014



3. DEVELOPED SOFTWARE FOR SENSOR MONITORING

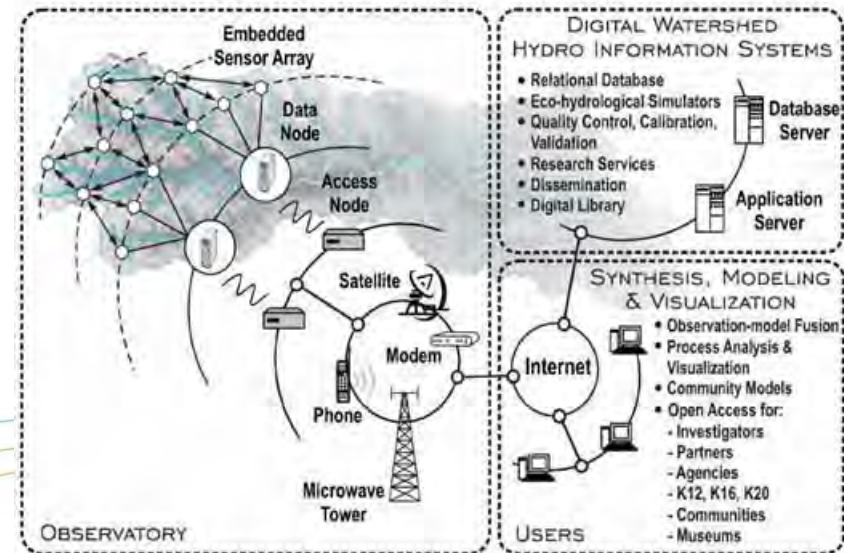
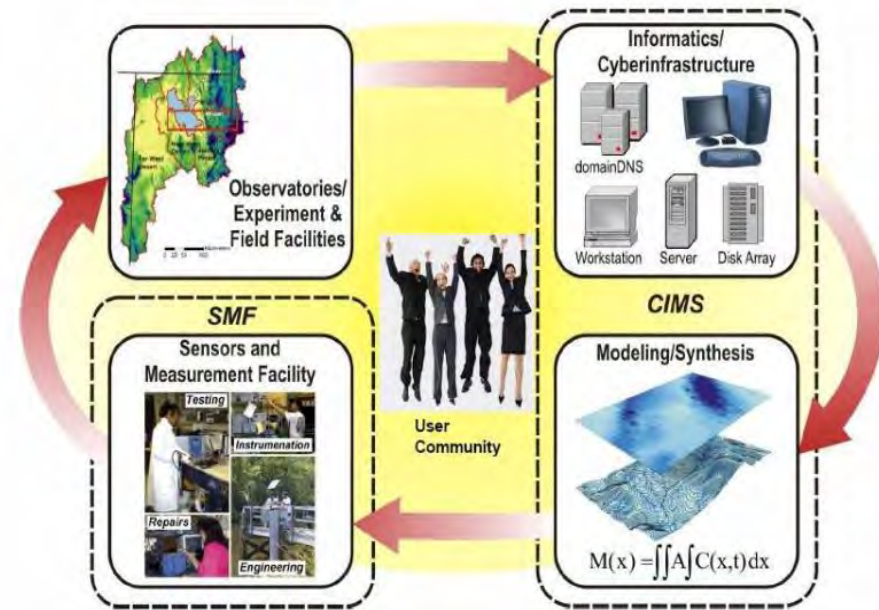
- ❑ VITO developed within an ESA (EU Space Agency) funded program the Sensorview software and assembled the Unmanned Surface Vessel Aqua Drone.
- ❑ The unique approach of Sensorview is the architecture around the integration of data collection, mobility, (near) real time data processing, data visualization and interpretation.
- ❑ The general architecture for Aqua Drone with 4D mapping services:



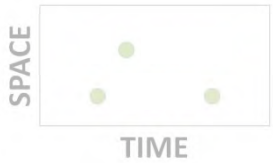
3. SENSORVIEW SOFTWARE

“Smart” software
for water quality analysis:

- ❑ Data quality assurance
- ❑ Screening/Alarm setting
- ❑ From data to information
- ❑ From information to decision support
- ❑ (VITO-wide) expertise with sensors → client support.



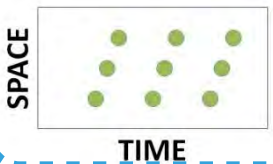
4. MOBILE AUTONOMOUS SENSOR PLATFORM: AQUA DRONE



- Points in time & space:
Spot samples + lab analysis



- Time series on fixed locations:
Fixed Sensors

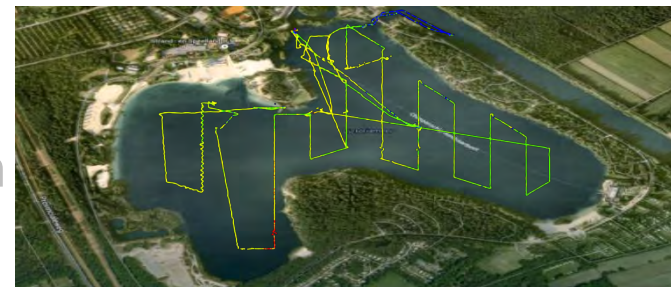
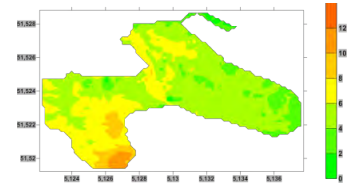


- Time-space series:
Mobile sensor platforms

Aqua Drone®

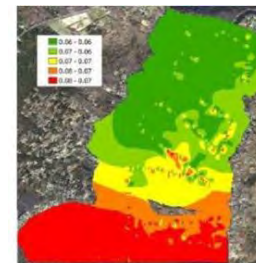


- Large Area coverage:
Remote sensing, earth observation

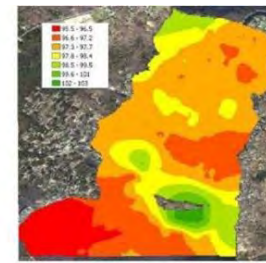


4. MOBILE PLATFORMS

- ❑ Aqua Drone operates autonomously and produces survey data. It is programmed with a mission plan and uses an advanced GPS system, along with onboard intelligence to retrieve the information. It can move itself auto correctively in case of obstacles on the designed track.
- ❑ Web based information system
- ❑ Generic interface between end user and sensor
- ❑ Bathymetry and water quality



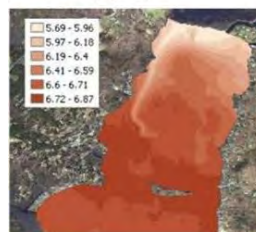
Salinity (psu)



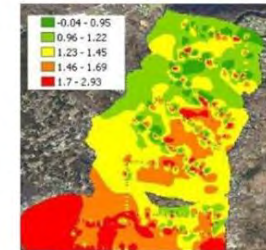
Dissolved Oxygen (% Sat)



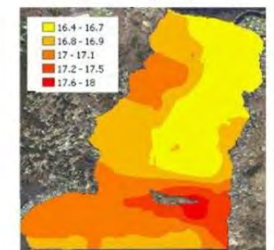
Blue-green Algae (RFU)



pH



Turbidity (NTU)



Temp (C)

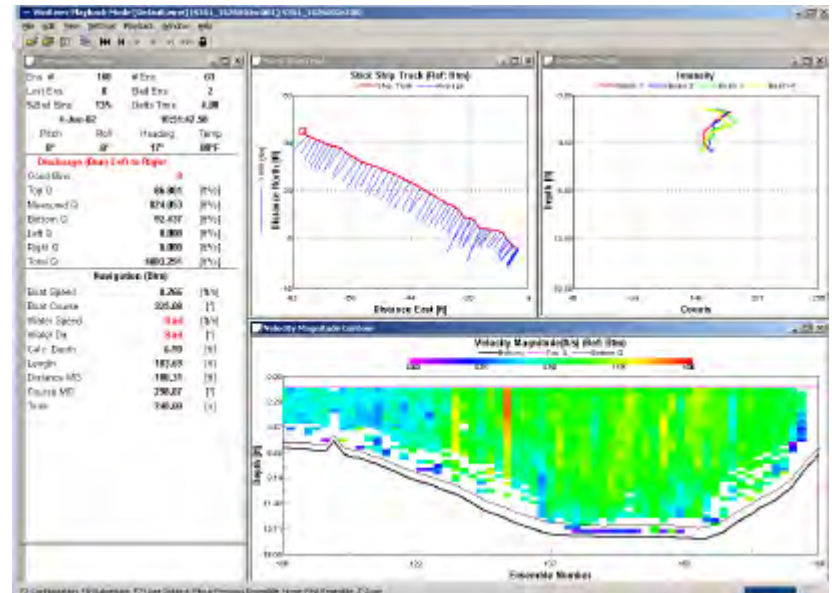
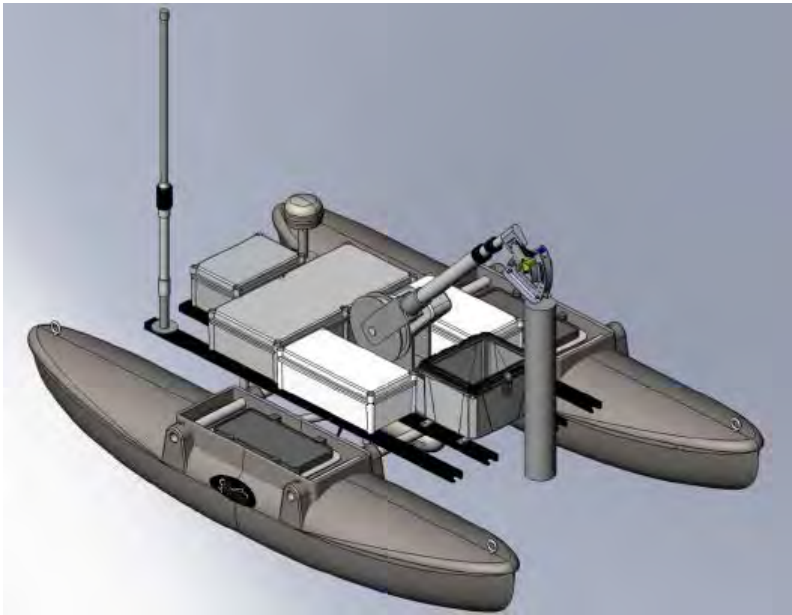
4. MOBILE PLATFORMS: WHEN USING THEM?

- ❑ When there is a need for high frequency temporal and spatial data; for instance elevated risk for human toxicity: drinking water, recreational water, fish/shellfish production sites. The sensors are used as part of an early warning system.
- ❑ Difficult to reach (shallow) areas.
- ❑ HAB areas with limited RS coverage (smog, clouds, shores).

4. MOBILE AUTONOMOUS SENSOR PLATFORM: AQUA DRONE

Sensors are mounted on an autonomous surface vessel (ASV):

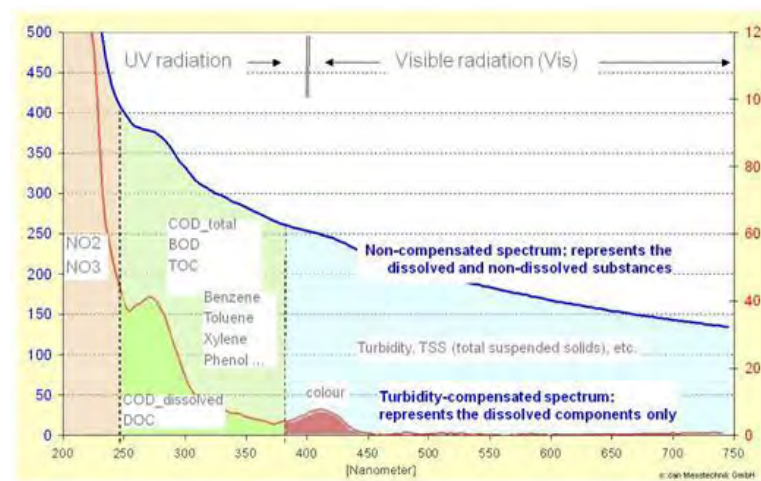
- ❑ Autopilot navigation based on way points & GPS
- ❑ Winch for water quality sensor measurements and sampling over depth.



4. MOBILE PLATFORM: SENSORS FOR ALGAE DETECTION

Sensors on board:

- ❑ YSI multi parameter water quality probe
- ❑ BBE fluoroprobe: Chlorophyll → class determination: green algae, cyano, diatoms, cryptophytes
- ❑ S:CAN spectrolyser: in-situ spectrometer for nitrate measurements in the visible UV spectrum
- ❑ ADCP: velocity

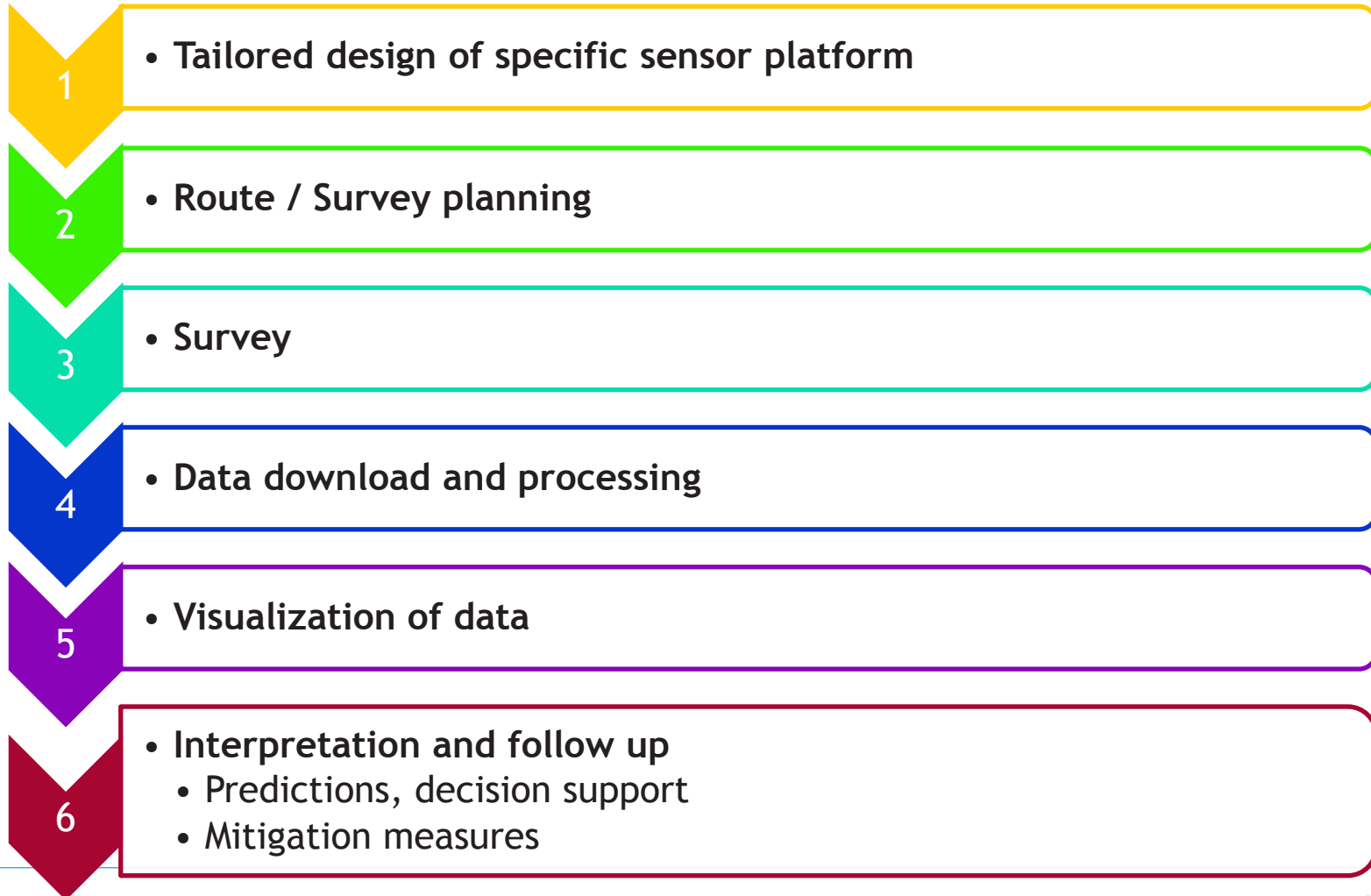


4. MOBILE AUTONOMOUS SENSOR PLATFORM: HARDWARE AQUA DRONE

Technical Specifications

USV Aqua Drone®		Units	Comment		
Mechanical					
Length	1.92	Meters	Single piece central hull construction		
Width	1.32	Meters			
Height	1	Meters	Height above water with RF antenna down		
Draft	0.35	Meters	Waterline to bottom of skeg		
Weight	109	kg	With payload		
Speed over water (max.)	5	kts			
Endurance					
1 kts	40	hr			
2 kts	16	hr			
3 kts	6	hr			
4 kts	1	hr			
Water quality parameters					
Dissolved oxygen	Conductivity (EC)	ORP (Redox)	Temperature	Salinity	pH
Depth	Turbidity	Nitrate Nitrogen	Nitrite Nitrogen	Chloride	Rhodamine
Blue-Green Algae - Phycocyanin	Blue-Green Algae - Phycoerythrin	Chlorophyll	SAC UV254 (organic load)		
Water quantity parameter				Optical backscatter	
ADCP					
Smart Water Sampling					
Triggered sampling when user-defined threshold is exceeded					
Camera (real time video +recording)					

5. AQUA DRONE: SERVICE STEPS



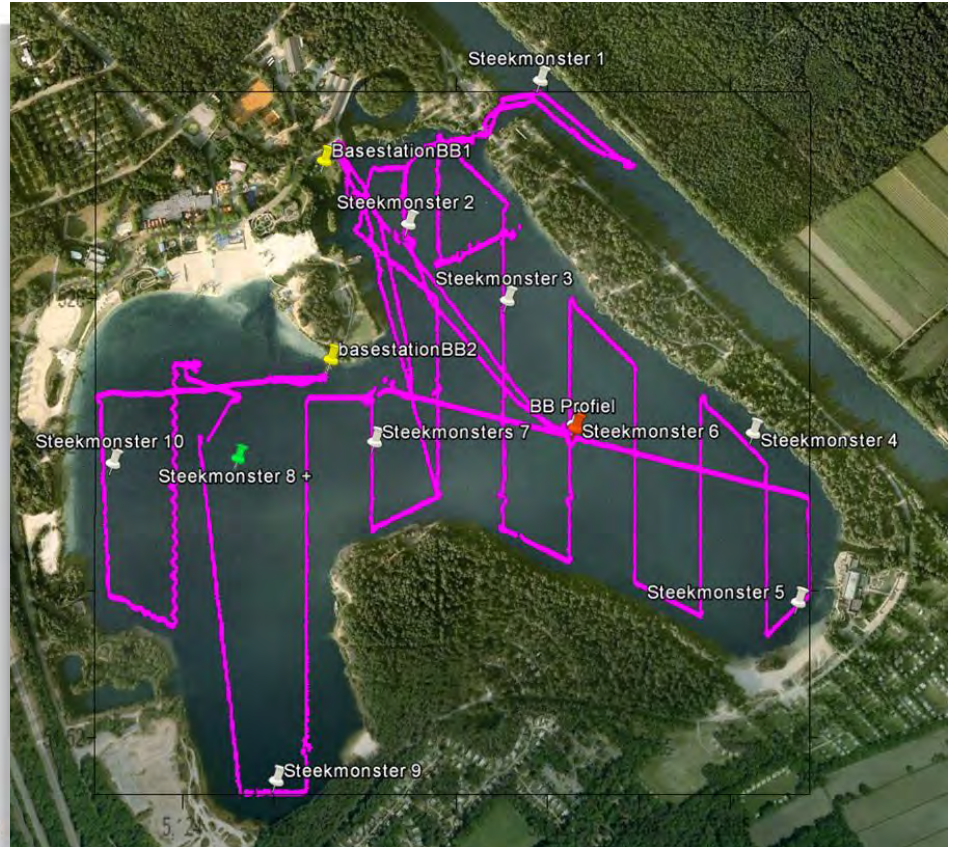
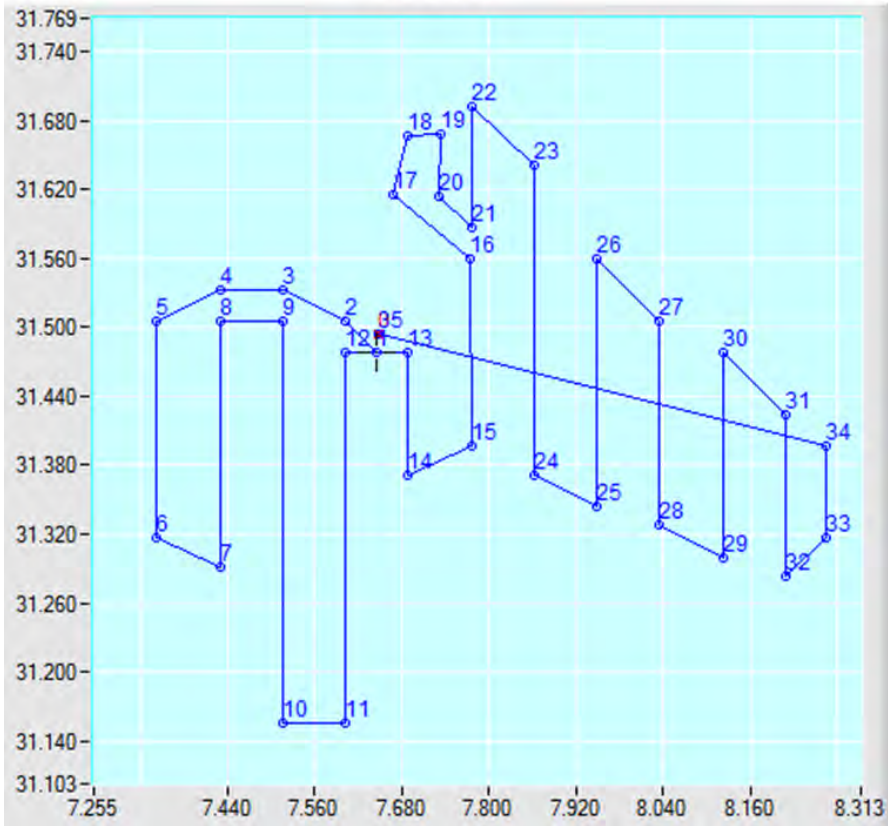
5. AQUA DRONE: TAILORED DESIGN

1



5. AQUA DRONE: SURVEY PLANNING

Mission Graph

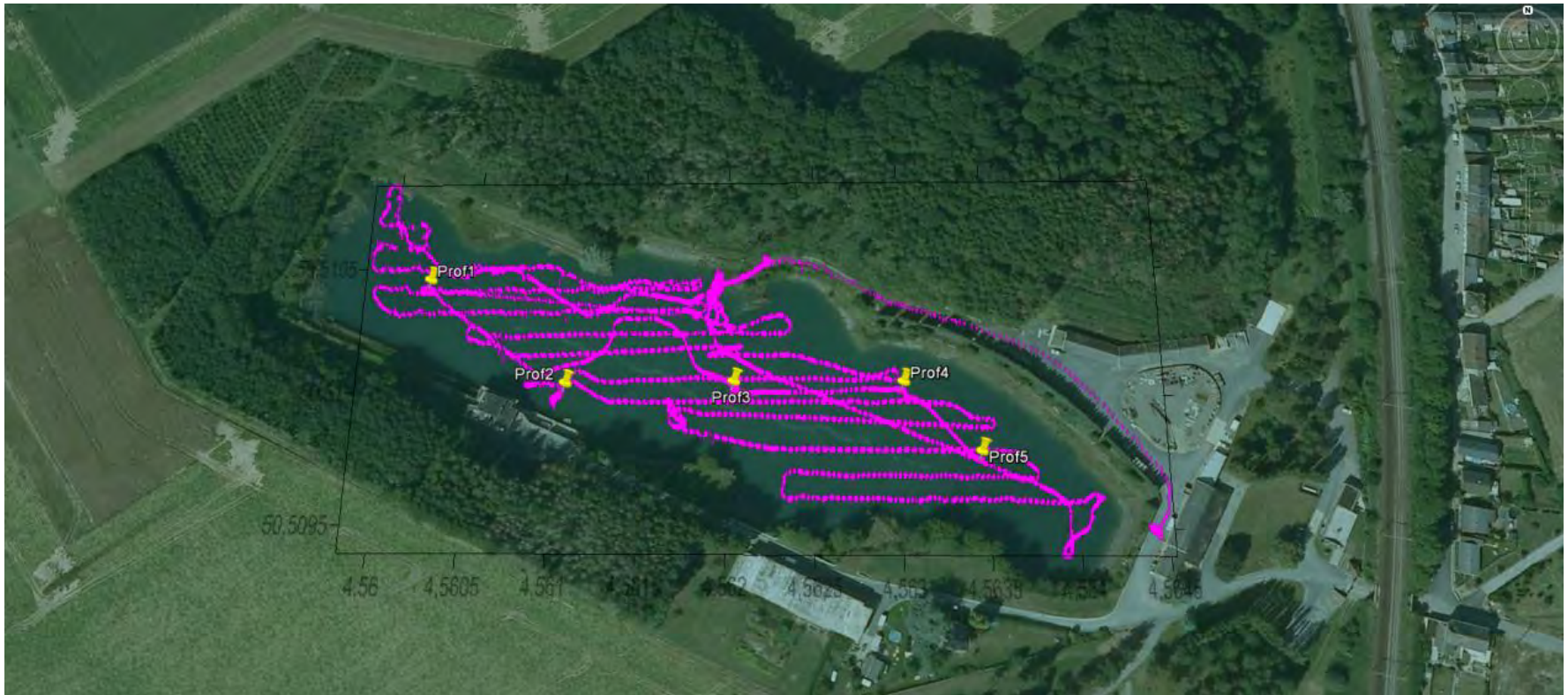


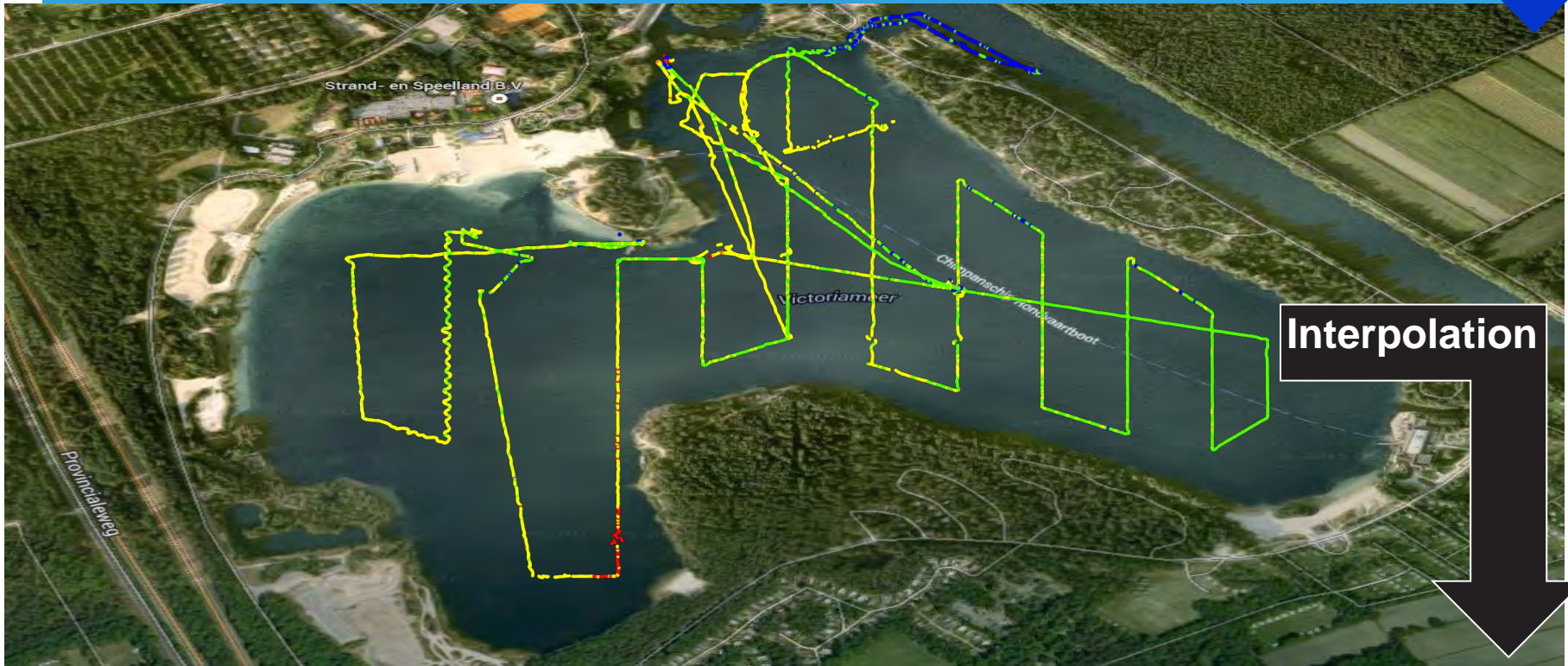


Base
station

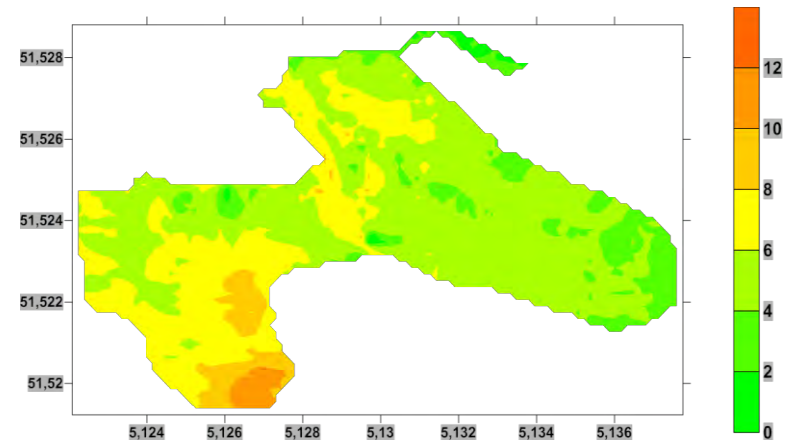
Aqua
Drone®



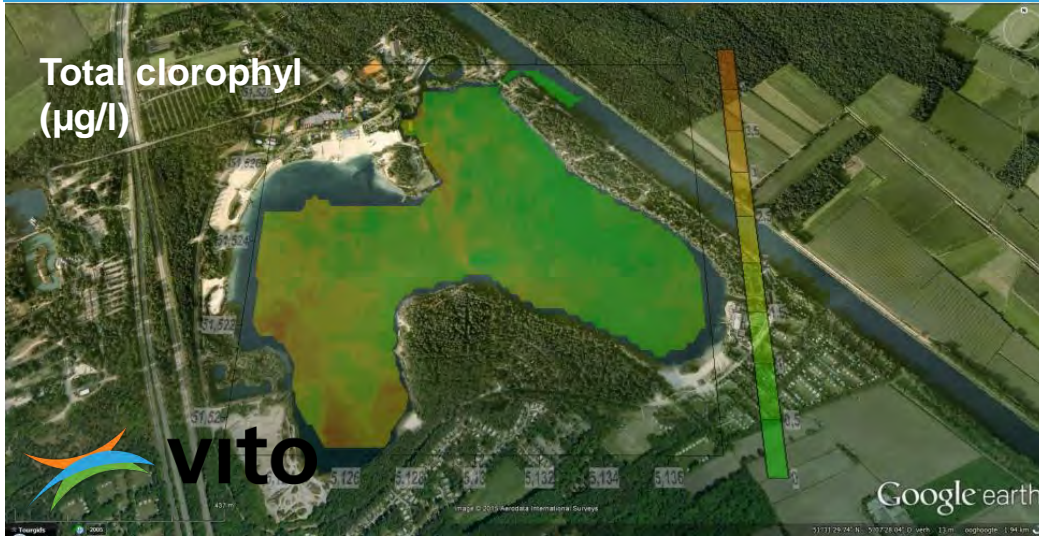


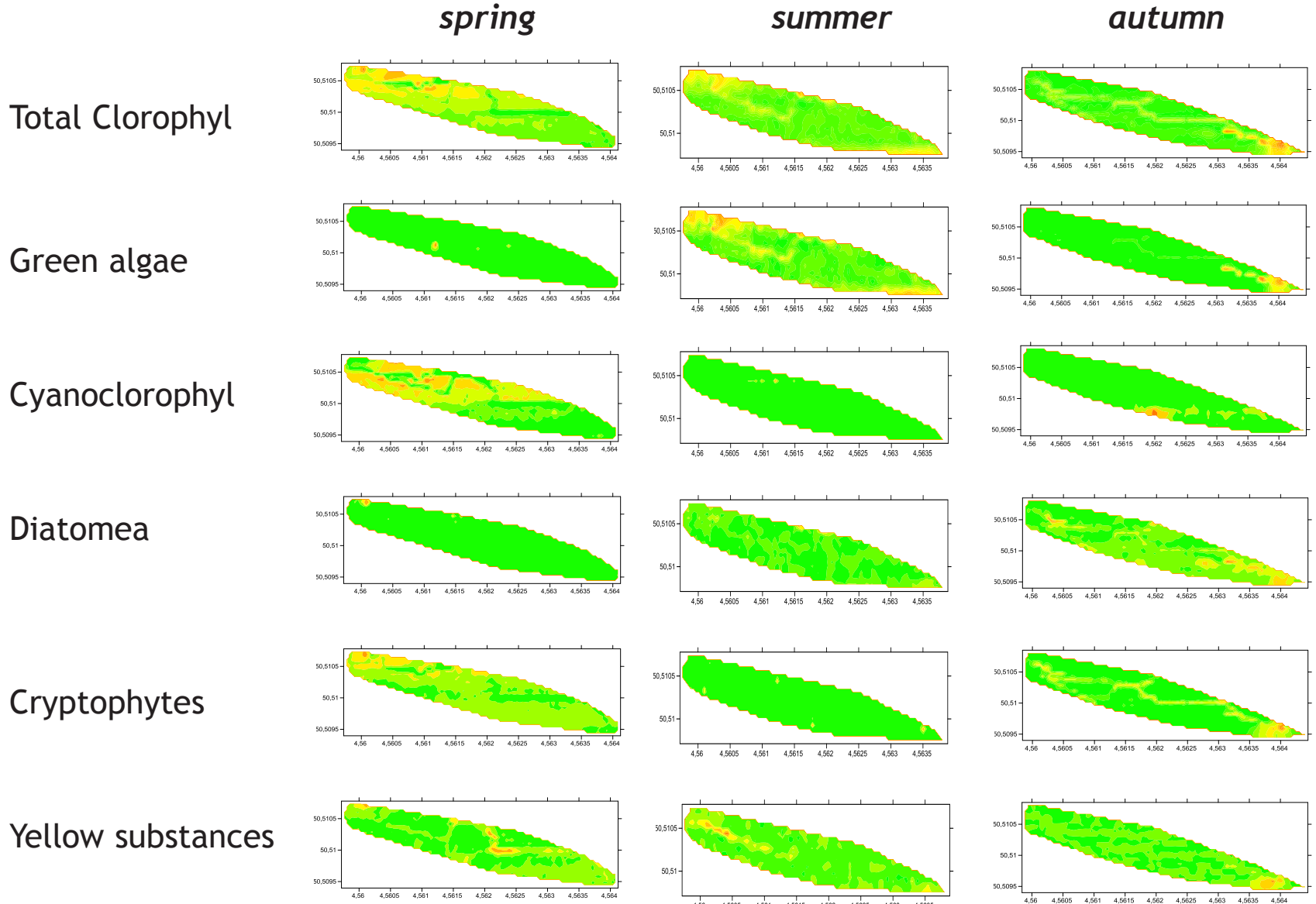


- ❑ Sensor measurements along the track
- ❑ High density point data set along navigation lines → interpolation (Kriging) → map



VISUALIZATION OF MONITORING RESULTS



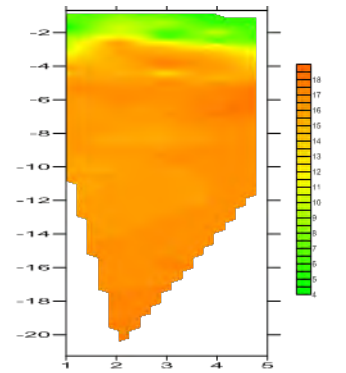
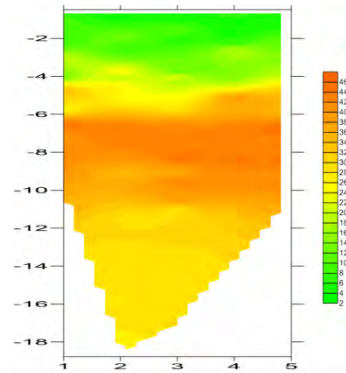
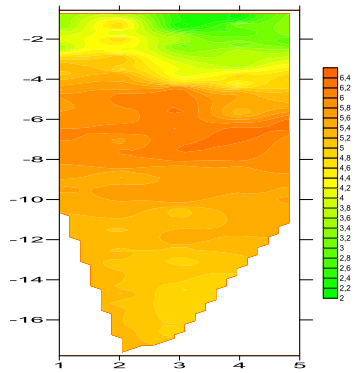


spring

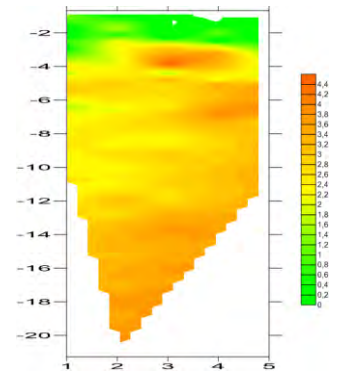
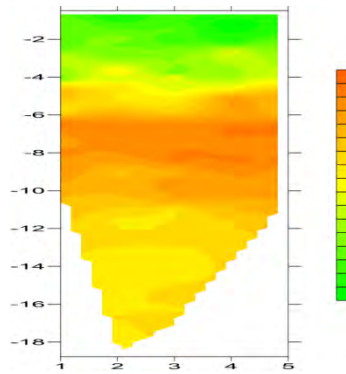
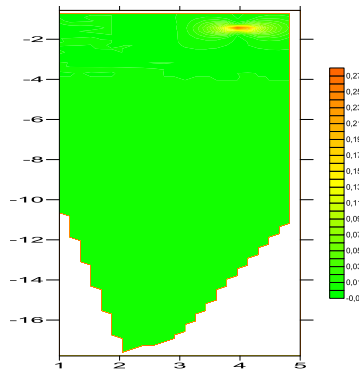
summer

autumn

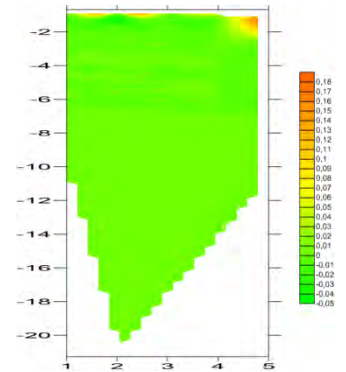
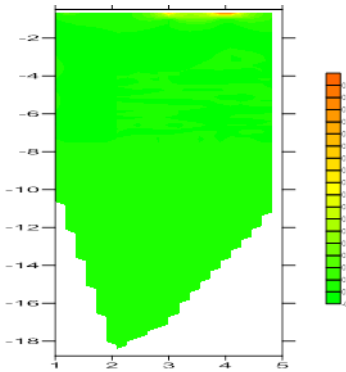
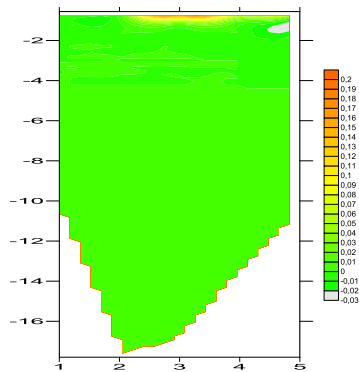
Total Chlorofyl



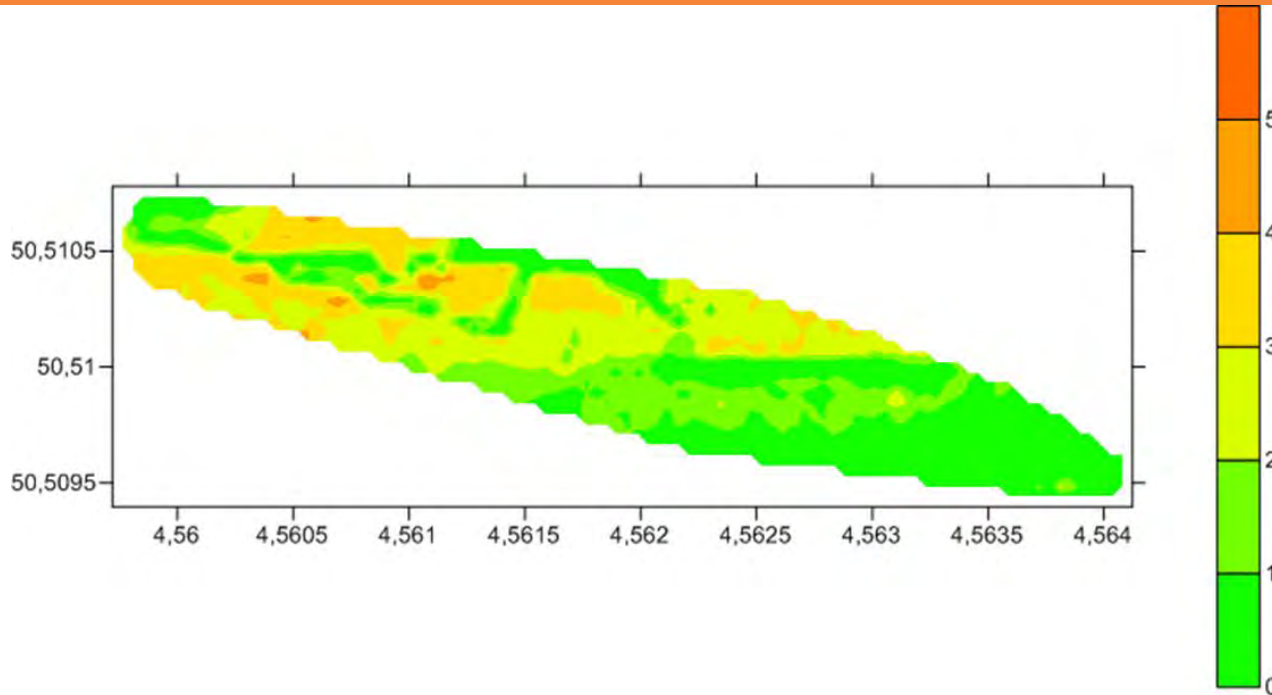
Green algae



Cyanoclorofyl

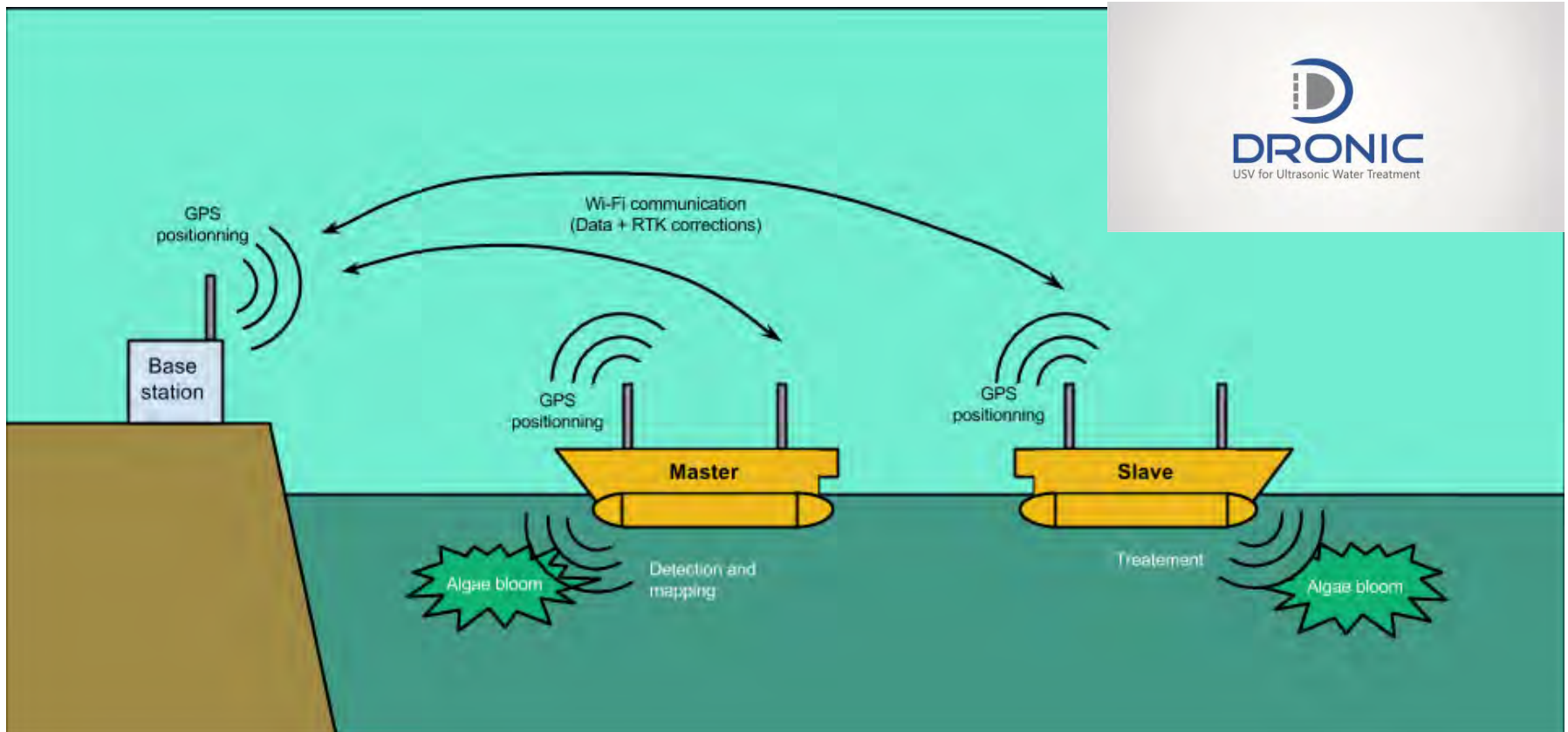


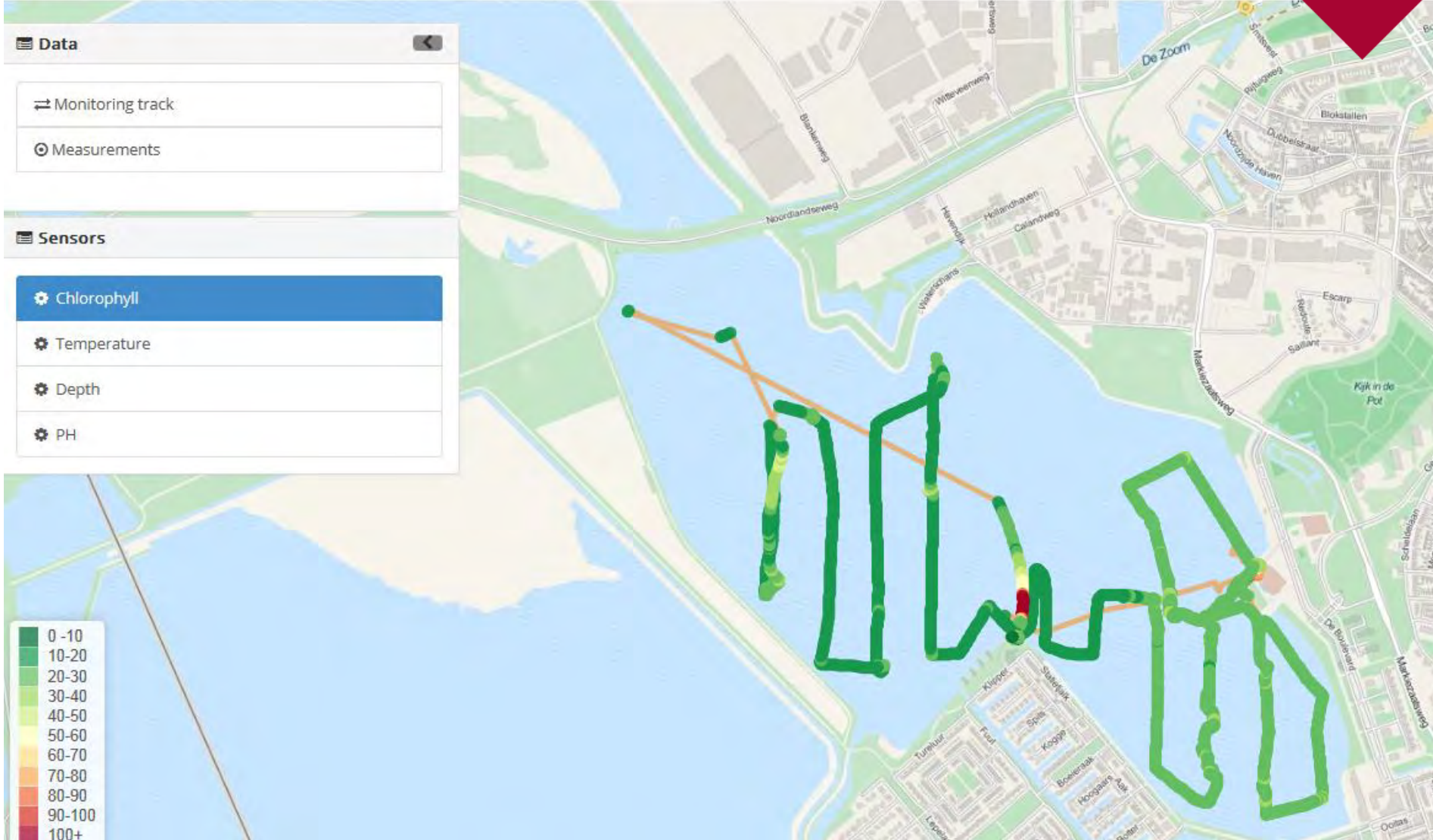
CYANOCOLOROPHYL ($\mu\text{G/L}$)



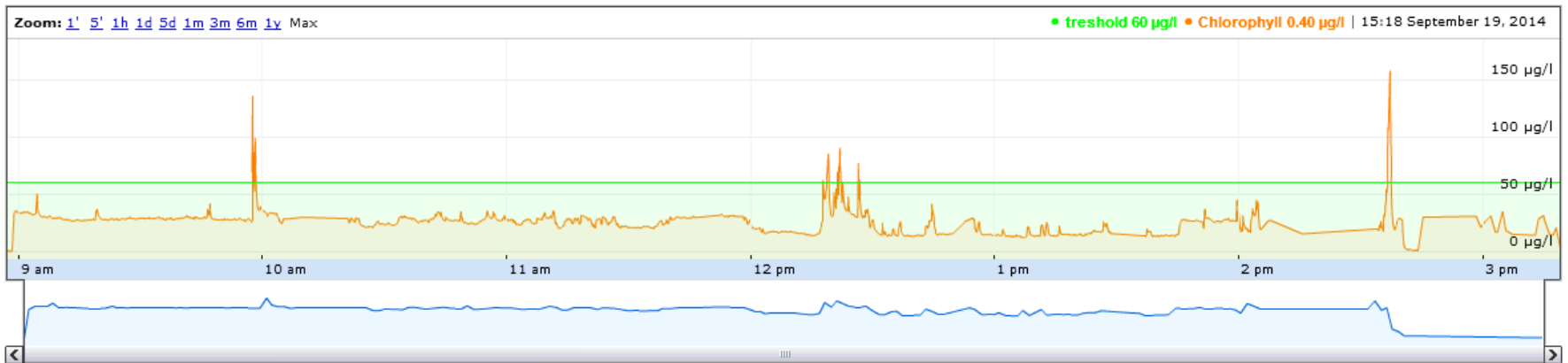
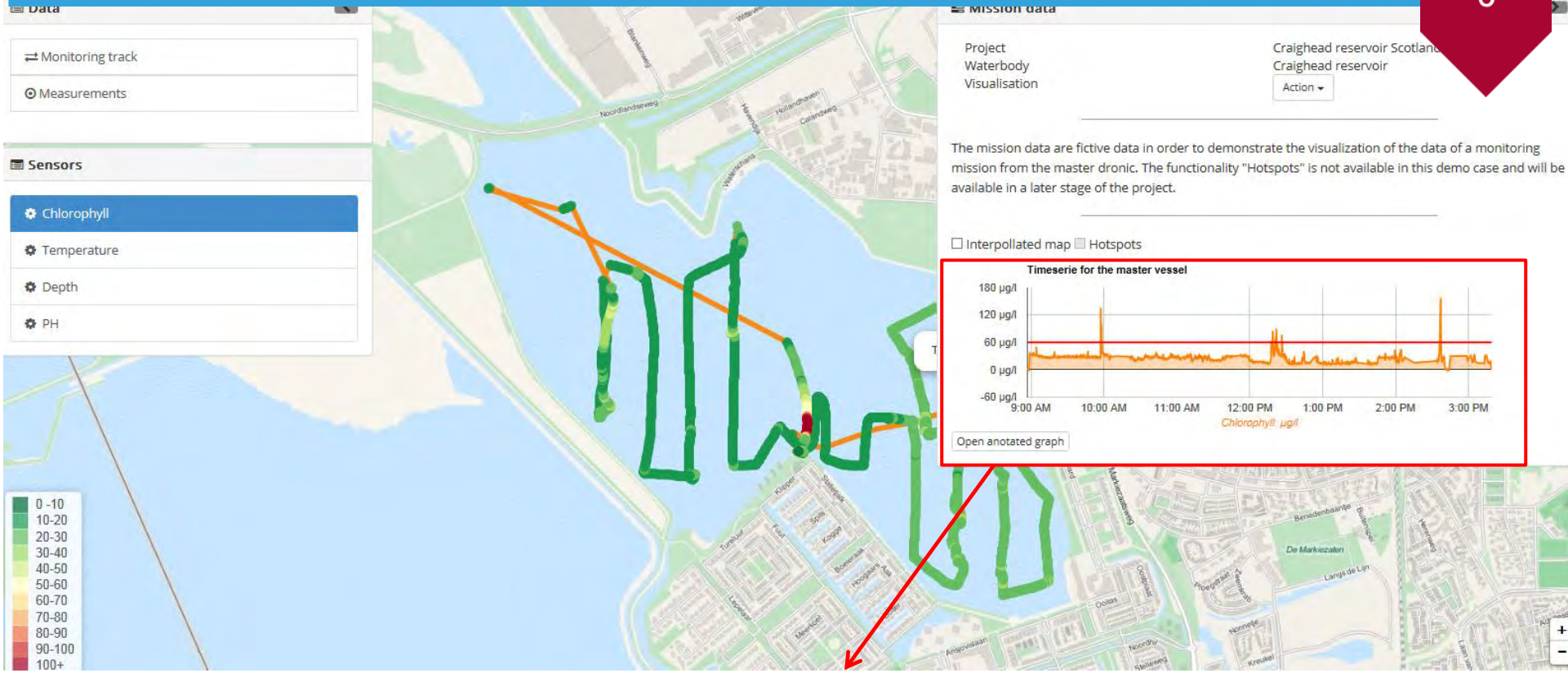
Dutch framework (blue algae protocol)	Cyano clorofyl
No Risk	< 12,5 $\mu\text{g/l}$
Low Risk (risk level 1)	12,5 $\mu\text{g/l}$ - 75 $\mu\text{g/l}$
Health risk (risk level 2)	> 75 $\mu\text{g/l}$

- Upstream reduction of N and P, flushing, ..
- Insitu treatment of algae of surveyed HAB hotspots (H₂O₂, ultrasonic, dredging, harvesting,..)





INTEGRATED MOBILE MONITORING, DECISION SUPPORT, TREATMENT

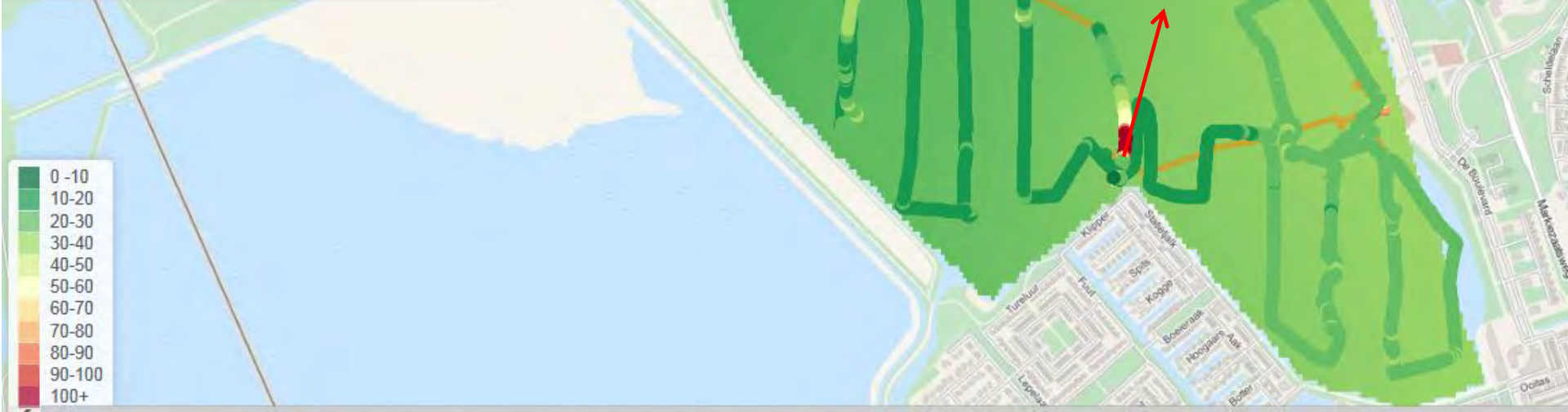


Data

- Monitoring track
- Measurements

Sensors

- Chlorophyll**
- Temperature
- Depth
- PH



SUMMARY

Mobile sensor platforms

- ❑ Successful proven method for gathering and processing high temporal and spatial resolution data (4D) through sensor platforms controlled by sensor software (near real time transfer).
- ❑ Use for rapid environmental assessment of risk areas that can be repeated in time on same locations
- ❑ Profiling and sampling in depth is possible
- ❑ User defined data sensors (flexibility): Algae or other water quality parameters, depth / velocity profiles.
- ❑ Use in areas with low RS coverage (clouds, smog, shores) and difficult access.
- ❑ Adaption to real time data transfer is in process.

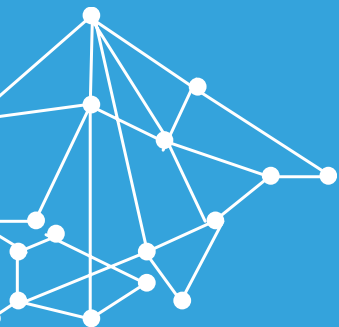
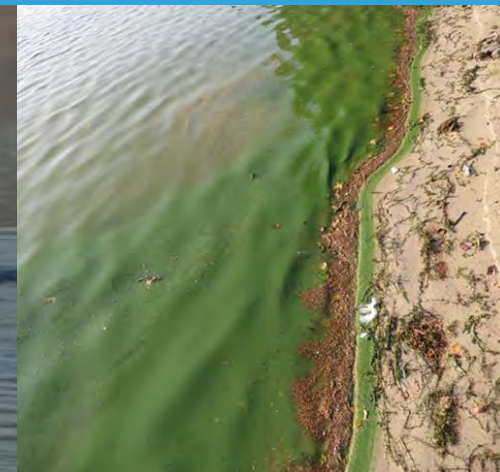
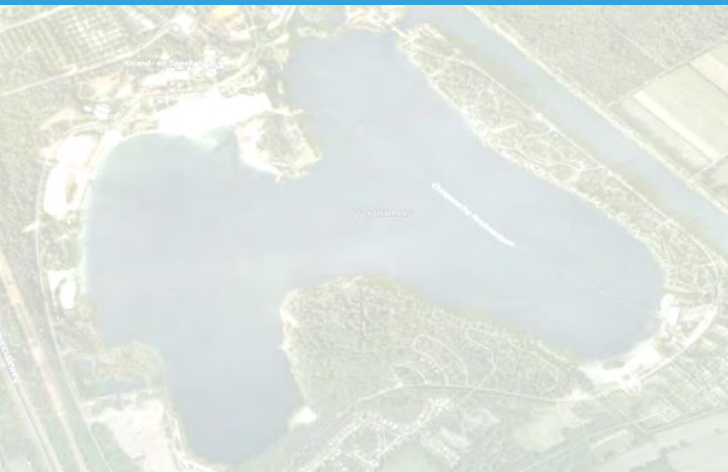
From monitoring to management

- ❑ Visualisation
 - Data set, graphs, maps
- ❑ Interpretation and decision support

EXTRA INFO

Dronic

- ❑ www.dronicproject.com



Questions ?

Jaap.vannes@vito.be
www.vito.be